

Stability conditions of unperturbed motion governed by the ternary differential system of Lyapunov-Darboux type with nonlinearities of fifth degree

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Abstract. In this paper, there was studied Lyapunov stability of the unperturbed motion for the ternary differential system with nonlinearities of fifth degree on a center-affine variety. The Lyapunov series was constructed and the stability conditions of the unperturbed motion governed by this system were determined in the critical case.

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Keywords: differential system, stability of unperturbed motion, critical equation, non-critical equation, Lyapunov series.

Condițiile de stabilitate a mișcării neperturbate guvernate de sistemul diferențial ternar de tip Lyapunov-Darboux cu nelinearități de gradul cinci

Rezumat. În lucrare a fost studiată stabilitatea după Lyapunov a mișcării neperturbate pentru sistemul diferențial ternar cu nelinearități de gradul cinci, pe o varietate centro-afină. A fost construită seria Lyapunov și determinate condițiile de stabilitate a mișcării neperturbate guvernate de acest sistem în cazul critic.

Cuvinte-cheie: sistem diferențial, stabilitatea mișcării neperturbate, ecuație critică, ecuație necritică, serie Lyapunov.

1. INTRODUCTION

We examine the three-dimensional differential system $s^3(1, 5)$ of unperturbed motion of the form

$$\frac{dx^j}{dt} = a_{\alpha}^j x^{\alpha} + a_{\alpha\beta\gamma\delta\mu}^j x^{\alpha} x^{\beta} x^{\gamma} x^{\delta} x^{\mu} \quad (j, \alpha, \beta, \gamma, \delta, \mu = \overline{1, 3}), \quad (1)$$

where $a_{\alpha\beta\gamma\delta\mu}^j$ is a symmetric tensor in the lower indices, by which a total convolution is done.

Definition 1.1. According to I. G. Malkin [1], we will say that the system (1) is critical if the characteristic equation of this system has one zero root, and all other roots of this equation have negative real parts.

Lemma 1.1. *The three-dimensional differential system (1) is critical if and only if the following center-affine invariant conditions hold*

$$L_{1,3} > 0, \quad L_{2,3} > 0, \quad L_{3,3} = 0, \quad (2)$$

where

$$L_{1,3} = -\theta_1, \quad L_{2,3} = \frac{1}{2}(\theta_1^2 - \theta_2), \quad L_{3,3} = \frac{1}{6}(-\theta_1^3 + 3\theta_1\theta_2 - 2\theta_3), \quad (3)$$

and

$$\theta_1 = a_\alpha^\alpha, \quad \theta_2 = a_\beta^\alpha a_\alpha^\beta, \quad \theta_3 = a_\gamma^\alpha a_\alpha^\beta a_\beta^\gamma. \quad (4)$$

Lemma 1.2. *In the case of conditions (2), by a center-affine transformation [2], the system (1) can be brought to the critical Lyapunov form*

$$\begin{aligned} \frac{dx^1}{dt} &= a_{\alpha\beta\gamma\delta\mu}^j x^\alpha x^\beta x^\gamma x^\delta x^\mu, \\ \frac{dx^j}{dt} &= a_\alpha^j x^\alpha + a_{\alpha\beta\gamma\delta\mu}^j x^\alpha x^\beta x^\gamma x^\delta x^\mu \quad (j = 2, 3; \alpha, \beta, \gamma, \delta, \mu = \overline{1, 3}), \end{aligned} \quad (5)$$

where the first equation from (5) is called the **critical equation** and the second one – the **non-critical equation**.

2. THE CRITICAL DIFFERENTIAL SYSTEM OF LYAPUNOV-DARBOUX TYPE WITH NONLINEARITIES OF FIFTH DEGREE

In the center-affine condition $\eta = a_{\beta\gamma\delta\mu\nu}^\alpha x^\beta x^\gamma x^\delta x^\mu x^\nu x^\tau y^\xi \varepsilon_{\alpha\tau\xi} \equiv 0$ [3], with notations

$$x^1 = x, \quad x^2 = y, \quad x^3 = z, \quad a_1^2 = p, \quad a_2^2 = q, \quad a_3^2 = r, \quad a_1^3 = s, \quad a_2^3 = m, \quad a_3^3 = n, \quad (6)$$

the system (5), it is a critical system of Lyapunov-Darboux type, of the form

$$\begin{aligned} \frac{dx}{dt} &= 5xR(x, y, z), \\ \frac{dy}{dt} &= px + qy + rz + 5yR(x, y, z), \\ \frac{dz}{dt} &= sx + my + nz + 5zR(x, y, z), \end{aligned} \quad (7)$$

where

$$\begin{aligned} R(x, y, z) &= a_1x^4 + a_2y^4 + a_3z^4 + 4a_4x^3y + 4a_5x^3z + 4a_6xy^3 + 4a_7xz^3 + 6a_8x^2y^2 + \\ &+ 6a_9x^2z^2 + 12a_{10}x^2yz + 12a_{11}xy^2z + 12a_{12}xyz^2 + 6a_{13}y^2z^2 + 4a_{14}y^3z + 4a_{15}yz^3, \end{aligned} \quad (8)$$

and $m, n, p, q, r, s, a_i (i = \overline{1, 15})$ are real arbitrary coefficients.

Remark 2.1. For the system (7), we have

$$L_{2,3} = nq - mr,$$

and according to conditions (2) these values are greater than zero.

Remark 2.2. Under the conditions of Remark 2.1, without loss of generality, we can assume that $nq \neq 0$.

Proof. We consider the center-affine substitution

$$\bar{x} = x, \quad \bar{y} = z, \quad \bar{z} = y. \quad (9)$$

It is easy to verify that in the case of substitution (9), we obtain that in system (7) the expression mr becomes nq . Taking into account Remark 2.1, we obtain that $nq \neq 0$. $\square$

We analyze the noncritical equations

$$\begin{aligned} px + qy + rz + 5y(a_1x^4 + a_2y^4 + a_3z^4 + 4a_4x^3y + 4a_5x^3z + 4a_6xy^3 + 4a_7xz^3 + \\ + 6a_8x^2y^2 + 6a_9x^2z^2 + 12a_{10}x^2yz + 12a_{11}xy^2z + 12a_{12}xyz^2 + 6a_{13}y^2z^2 + \\ + 4a_{14}y^3z + 4a_{15}yz^3) = 0, \\ sx + my + nz + 5z(a_1x^4 + a_2y^4 + a_3z^4 + 4a_4x^3y + 4a_5x^3z + 4a_6xy^3 + 4a_7xz^3 + \\ + 6a_8x^2y^2 + 6a_9x^2z^2 + 12a_{10}x^2yz + 12a_{11}xy^2z + 12a_{12}xyz^2 + 6a_{13}y^2z^2 + \\ + 4a_{14}y^3z + 4a_{15}yz^3) = 0. \end{aligned} \quad (10)$$

Then from the first relation of (10) we express y , and from the second relation we express z

$$\begin{aligned} y = -\frac{p}{q}x - \frac{r}{q}z - \frac{5}{q}y(a_1x^4 + a_2y^4 + a_3z^4 + 4a_4x^3y + 4a_5x^3z + 4a_6xy^3 + 4a_7xz^3 + \\ + 6a_8x^2y^2 + 6a_9x^2z^2 + 12a_{10}x^2yz + 12a_{11}xy^2z + 12a_{12}xyz^2 + 6a_{13}y^2z^2 + \\ + 4a_{14}y^3z + 4a_{15}yz^3), \\ z = -\frac{s}{n}x - \frac{m}{n}y - \frac{5}{n}z(a_1x^4 + a_2y^4 + a_3z^4 + 4a_4x^3y + 4a_5x^3z + 4a_6xy^3 + 4a_7xz^3 + \\ + 6a_8x^2y^2 + 6a_9x^2z^2 + 12a_{10}x^2yz + 12a_{11}xy^2z + 12a_{12}xyz^2 + 6a_{13}y^2z^2 + \\ + 4a_{14}y^3z + 4a_{15}yz^3). \end{aligned} \quad (11)$$

We seek y and z as a holomorphic functions of x . Then we can write

$$\begin{aligned} y(x) &= A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots, \\ z(x) &= B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots \end{aligned} \quad (12)$$

Substituting (12) into (11) we have

$$\begin{aligned}
 A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots = & -\frac{p}{q}x - \frac{r}{q}(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + \\
 & + B_5x^5 + \dots) - \frac{5}{q}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)[a_1x^4 + a_2(A_1x + A_2x^2 + \\
 & + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^4 + a_3(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^4 + \\
 & + 4a_4x^3(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots) + 4a_5x^3(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + \\
 & + B_5x^5 + \dots) + 4a_6x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^3 + 4a_7x(B_1x + B_2x^2 + \\
 & + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^3 + 6a_8x^2(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2 + \\
 & + 6a_9x^2(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^2 + 12a_{10}x^2(A_1x + A_2x^2 + A_3x^3 + \\
 & + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + 12a_{11}x(A_1x + A_2x^2 + \\
 & + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + \\
 & + 12a_{12}x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + \\
 & + B_5x^5 + \dots)^2 + 6a_{13}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2(B_1x + B_2x^2 + B_3x^3 + \\
 & + B_4x^4 + B_5x^5 + \dots)^2 + 4a_{14}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^3(B_1x + B_2x^2 + \\
 & + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + 4a_{15}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)(B_1x + \\
 & + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^3],
 \end{aligned}$$

$$\begin{aligned}
 B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots = & -\frac{s}{n}x - \frac{m}{n}(A_1x + A_2x^2 + A_3x^3 + \\
 & + A_4x^4 + A_5x^5 + \dots) - \frac{5}{n}(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)[a_1x^4 + a_2(A_1x + \\
 & + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^4 + a_3(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^4 + \\
 & + 4a_4x^3(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots) + 4a_5x^3(B_1x + B_2x^2 + B_3x^3 + \\
 & + B_4x^4 + B_5x^5 + \dots) + 4a_6x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^3 + 4a_7x(B_1x + \\
 & + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^3 + 6a_8x^2(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2 + \\
 & + 6a_9x^2(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^2 + 12a_{10}x^2(A_1x + A_2x^2 + A_3x^3 + \\
 & + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + 12a_{11}x(A_1x + A_2x^2 + \\
 & + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + \\
 & + 12a_{12}x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + \\
 & + B_5x^5 + \dots)^2 + 6a_{13}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2(B_1x + B_2x^2 + B_3x^3 + \\
 & + B_4x^4 + B_5x^5 + \dots)^2 + 4a_{14}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^3(B_1x + B_2x^2 +
 \end{aligned}$$

$$+B_3x^3 + B_4x^4 + B_5x^5 + \dots) + 4a_{15}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^3],$$

This implies that

$$\begin{aligned} A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots &= -\frac{p+rB_1}{q}x - \frac{rB_2}{q}x^2 - \frac{rB_3}{q}x^3 - \frac{rB_4}{q}x^4 - \\ &\quad - \frac{1}{q}(5a_1A_1 + 20a_4A_1^2 + 30a_8A_1^3 + 20a_6A_1^4 + 5a_2A_1^5 + 60a_{10}A_1^2B_1 + 60a_{11}A_1^3B_1 + \\ &\quad + 20a_{14}A_1^4B_1 + 20a_5A_1B_1 + 60a_{12}A_1^2B_1^2 + 30a_{13}A_1^3B_1^2 + 30a_9A_1B_1^2 + 20a_{15}A_1^2B_1^3 + \\ &\quad + 20a_7A_1B_1^3 + 5a_3A_1B_1^4 + rB_5)x^5 + \dots \\ B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots &= -\frac{mA_1+s}{n}x - \frac{mA_2}{n}x^2 - \frac{mA_3}{n}x^3 - \frac{mA_4}{n}x^4 - \\ &\quad - \frac{1}{n}(5a_2A_1^4B_1 + 20a_4A_1B_1 + 20a_6A_1^3B_1 + 30a_8A_1^2B_1 + 60a_{10}A_1B_1^2 + 60a_{11}A_1^2B_1^2 + \\ &\quad + 20a_{14}A_1^3B_1^2 + 60a_{12}A_1B_1^3 + 30a_{13}A_1^2B_1^3 + 20a_{15}A_1B_1^4 + mA_5 + 5a_1B_1 + 20a_5B_1^2 + \\ &\quad + 30a_9B_1^3 + 20a_7B_1^4 + 5a_3B_1^5)x^5 + \dots \end{aligned}$$

From this identity we have

$$\begin{aligned} A_1 &= \frac{rs-np}{nq-mr}, \quad B_1 = \frac{mp-qs}{nq-mr}; \quad A_2 = B_2 = A_3 = B_3 = A_4 = B_4 = 0, \\ A_5 &= -\frac{5}{nq-mr}(a_1 + 4a_4A_1 + 6a_8A_1^2 + 4a_6A_1^3 + a_2A_1^4 + 12a_{10}A_1B_1 + \\ &\quad + 12a_{11}A_1^2B_1 + 4a_{14}A_1^3B_1 + 4a_5B_1 + 12a_{12}A_1B_1^2 + 6a_{13}A_1^2B_1^2 + 6a_9B_1^2 + 4a_{15}A_1B_1^3 + \\ &\quad + 4a_7B_1^3 + a_3B_1^4)(nA_1 - rB_1), \\ B_5 &= \frac{5}{nq-mr}(a_1 + 4a_4A_1 + 6a_8A_1^2 + 4a_6A_1^3 + a_2A_1^4 + 12a_{10}A_1B_1 + \\ &\quad + 12a_{11}A_1^2B_1 + 4a_{14}A_1^3B_1 + 4a_5B_1 + 12a_{12}A_1B_1^2 + 6a_{13}A_1^2B_1^2 + 6a_9B_1^2 + 4a_{15}A_1B_1^3 + \\ &\quad + 4a_7B_1^3 + a_3B_1^4)(mA_1 - qB_1), \\ A_6 &= B_6 = A_7 = B_7 = A_8 = B_8 = 0, \\ A_9 &= -\frac{5}{nq-mr}[(a_1 + 4a_4A_1 + 6a_8A_1^2 + 4a_6A_1^3 + a_2A_1^4 + 12a_{10}A_1B_1 + \\ &\quad + 12a_{11}A_1^2B_1 + 4a_{14}A_1^3B_1 + 4a_5B_1 + 12a_{12}A_1B_1^2 + 6a_{13}A_1^2B_1^2 + 6a_9B_1^2 + 4a_{15}A_1B_1^3 + \\ &\quad + 4a_7B_1^3 + a_3B_1^4)(nA_5 - rB_5) + 4(a_2A_1^3A_5 + a_4A_5 + 3a_6A_1^2A_5 + 3a_8A_1A_5 + \\ &\quad + 3a_{10}A_5B_1 + 6a_{11}A_1A_5B_1 + 3a_{14}A_1^2A_5B_1 + 3a_{12}A_5B_1^2 + 3a_{13}A_1A_5B_1^2 + \\ &\quad + a_{15}A_5B_1^3 + 3a_{10}A_1B_5 + 3a_{11}A_1^2B_5 + a_{14}A_1^3B_5 + a_5B_5 + 6a_{12}A_1B_1B_5 + 3a_{13}A_1^2B_1B_5 + \\ &\quad + 3a_9B_1B_5 + 3a_{15}A_1B_1^2B_5 + 3a_7B_1^2B_5 + a_3B_1^3B_5)(nA_1 - rB_1)], \end{aligned}$$

$$\begin{aligned}
 B_9 = \frac{5}{nq - mr} & [(a_1 + 4a_4A_1 + 6a_8A_1^2 + 4a_6A_1^3 + a_2A_1^4 + 12a_{10}A_1B_1 + \\
 & + 12a_{11}A_1^2B_1 + 4a_{14}A_1^3B_1 + 4a_5B_1 + 12a_{12}A_1B_1^2 + 6a_{13}A_1^2B_1^2 + 6a_9B_1^2 + \\
 & + 4a_{15}A_1B_1^3 + 4a_7B_1^3 + a_3B_1^4)(mA_5 - qB_5) + 4(a_2A_1^3A_5 + a_4A_5 + \\
 & + 3a_6A_1^2A_5 + 3a_8A_1A_5 + 3a_{10}A_5B_1 + 6a_{11}A_1A_5B_1 + 3a_{14}A_1^2A_5B_1 + \\
 & + 3a_{12}A_5B_1^2 + 3a_{13}A_1A_5B_1^2 + a_{15}A_5B_1^3 + 3a_{10}A_1B_5 + 3a_{11}A_1^2B_5 + a_{14}A_1^3B_5 + \\
 & + a_5B_5 + 6a_{12}A_1B_1B_5 + 3a_{13}A_1^2B_1B_5 + 3a_9B_1B_5 + 3a_{15}A_1B_1^2B_5 + \\
 & + 3a_7B_1^2B_5 + a_3B_1^3B_5)(mA_1 - qB_1)], \\
 A_{10} = B_{10} = A_{11} = B_{11} = 0, \dots
 \end{aligned} \tag{13}$$

Substituting (12) into the right-hand sides of the critical differential equations (7), we get the following identity

$$\begin{aligned}
 C_1x + C_2x^2 + C_3x^3 + C_4x^4 + C_5x^5 + \dots = & 5x(a_1x^4 + a_2y^4 + a_3z^4 + 4a_4x^3y + 4a_5x^3z + \\
 & + 4a_6xy^3 + 4a_7xz^3 + 6a_8x^2y^2 + 6a_9x^2z^2 + 12a_{10}x^2yz + 12a_{11}xy^2z + 12a_{12}xyz^2 + \\
 & + 6a_{13}y^2z^2 + 4a_{14}y^3z + 4a_{15}yz^3),
 \end{aligned}$$

or in detailed form

$$\begin{aligned}
 & C_1x + C_2x^2 + C_3x^3 + C_4x^4 + C_5x^5 + \dots = \\
 & = 5x[a_1x^4 + a_2(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^4 + a_3(B_1x + B_2x^2 + B_3x^3 + \\
 & + B_4x^4 + B_5x^5 + \dots)^4 + 4a_4x^3(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots) + \\
 & + 4a_5x^3(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + 4a_6x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + \\
 & + A_5x^5 + \dots)^3 + 4a_7xz(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^3 + 6a_8x^2(A_1x + A_2x^2 + \\
 & + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2 + 6a_9x^2(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^2 + \\
 & + 12a_{10}x^2(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + \\
 & + B_5x^5 + \dots) + 12a_{11}x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2(B_1x + B_2x^2 + B_3x^3 + \\
 & + B_4x^4 + B_5x^5 + \dots) + 12a_{12}x(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)(B_1x + B_2x^2 + \\
 & + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^2 + 6a_{13}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \dots)^2(B_1x + \\
 & + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^2 + 4a_{14}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + A_5x^5 + \\
 & + \dots)^3(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots) + 4a_{15}(A_1x + A_2x^2 + A_3x^3 + A_4x^4 + \\
 & + A_5x^5 + \dots)(B_1x + B_2x^2 + B_3x^3 + B_4x^4 + B_5x^5 + \dots)^3].
 \end{aligned}$$

From here, we obtain

$$\begin{aligned}
 C_1 &= C_2 = C_3 = C_4 = 0, \\
 C_5 &= 5(a_1 + 4a_4A_1 + 6a_8A_1^2 + 4a_6A_1^3 + a_2A_1^4 + 12a_{10}A_1B_1 + 12a_{11}A_1^2B_1 + \\
 &\quad + 4a_{14}A_1^3B_1 + 4a_5B_1 + 12a_{12}A_1B_1^2 + 6a_{13}A_1^2B_1^2 + 6a_9B_1^2 + 4a_{15}A_1B_1^3 + \\
 &\quad + 4a_7B_1^3 + a_3B_1^4), \\
 C_6 &= 20(a_2A_1^3A_2 + a_4A_2 + 3a_6A_1^2A_2 + 3a_8A_1A_2 + 3a_{10}A_2B_1 + 6a_{11}A_1A_2B_1 + \\
 &\quad + 3a_{14}A_1^2A_2B_1 + 3a_{12}A_2B_1^2 + 3a_{13}A_1A_2B_1^2 + a_{15}A_2B_1^3 + 3a_{10}A_1B_2 + 3a_{11}A_1^2B_2 + \\
 &\quad + a_{14}A_1^3B_2 + a_5B_2 + 6a_{12}A_1B_1B_2 + 3a_{13}A_1^2B_1B_2 + 3a_9B_1B_2 + 3a_{15}A_1B_1^2B_2 + \\
 &\quad + 3a_7B_1^2B_2 + a_3B_1^3B_2), \\
 C_7 &= 10(3a_2A_1^2A_2^2 + 2a_2A_1^3A_3 + 2a_4A_3 + 6a_6A_1A_2^2 + 6a_6A_1^2A_3 + 3a_8A_2^2 + \\
 &\quad + 6a_8A_1A_3 + 6a_{11}A_2^2B_1 + 6a_{14}A_1A_2^2B_1 + 6a_{10}A_3B_1 + 12a_{11}A_1A_3B_1 + \\
 &\quad + 6a_{14}A_1^2A_3B_1 + 3a_{13}A_2^2B_1^2 + 6a_{12}A_3B_1^2 + 6a_{13}A_1A_3B_1^2 + 2a_{15}A_3B_1^3 + 6a_{10}A_2B_2 + \\
 &\quad + 12a_{11}A_1A_2B_2 + 6a_{14}A_1^2A_2B_2 + 12a_{12}A_2B_1B_2 + 12a_{13}A_1A_2B_1B_2 + \\
 &\quad + 6a_{15}A_2B_1^2B_2 + 6a_{12}A_1B_2^2 + 3a_{13}A_1^2B_2^2 + 3a_9B_2^2 + 6a_{15}A_1B_1B_2^2 + 6a_7B_1B_2^2 + \\
 &\quad + 3a_3B_1^2B_2^2 + 6a_{10}A_1B_3 + 6a_{11}A_1^2B_3 + 2a_{14}A_1^3B_3 + 2a_5B_3 + 12a_{12}A_1B_1B_3 + \\
 &\quad + 6a_{13}A_1^2B_1B_3 + 6a_9B_1B_3 + 6a_{15}A_1B_1^2B_3 + 6a_7B_1^2B_3 + 2a_3B_1^3B_3), \dots
 \end{aligned} \tag{14}$$

3. THE STABILITY CONDITIONS OF UNPERTURBED MOTION FOR THE TERNARY DIFFERENTIAL SYSTEM OF LYAPUNOV-DARBOUX TYPE WITH NONLINEARITIES OF FIFTH DEGREE

We will introduce the following notation:

$$\begin{aligned}
 M &= a_1 + 4a_4A_1 + 6a_8A_1^2 + 4a_6A_1^3 + a_2A_1^4 + 12a_{10}A_1B_1 + 12a_{11}A_1^2B_1 + \\
 &\quad + 4a_{14}A_1^3B_1 + 4a_5B_1 + 12a_{12}A_1B_1^2 + 6a_{13}A_1^2B_1^2 + 6a_9B_1^2 + 4a_{15}A_1B_1^3 + \\
 &\quad + 4a_7B_1^3 + a_3B_1^4,
 \end{aligned} \tag{15}$$

According to Lyapunov Theorem [4, §32], we have

Theorem 3.1. *Let the critical system (7) be given on the invariant variety. The stability of the unperturbed motion is described by one of the following three possible cases:*

- I.** *If $M > 0$, then the unperturbed motion is **unstable**;*
- II.** *If $M < 0$, then the unperturbed motion is **stable**;*
- III.** *If $M = 0$, then the unperturbed motion is **stable**.*

In the last case, the unperturbed motion belongs to some continuous series of stabilized motions. Moreover, this motion is asymptotically stable.

Proof. According to Lyapunov Theorem [4], we analyze the coefficients of the series (14). The stability or the instability of the unperturbed motion of the system (7) is determined by the sign of expression C_5 , and we get Cases I and II.

Therefore, if $C_5 = 0$, then all $A_i = B_i = 0$ ($\forall i$), so we get Case III of this theorem. $\square$

Remark 3.1. *Theorem 3.1 was presented at the 31st Conference on Applied and Industrial Mathematics (CAIM-2024) [6].*

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